

ECE 278 Final project

Normalized Cuts and Image Segmentation

Baris Sumengen

Jelena Tešić

Vision Research Lab

Electrical and Computer engineering





Outline

- Introduction
- Graph Partitioning
- Grouping Algorithm
- Experiments
- Results
- Related Approaches
- Conclusion

Introduction

- Segmentation method based on the paper by Jianbo Shi and Jitendra Malik, CVPR 1997
- Usage of low-level coherence of image attributes for candidate partitions generation
- Set of points is presented as a weighted undirected graph $\mathbf{G} = (\mathbf{V}, \mathbf{E})$
 - Nodes of the graph – points in the feature space
 - Weight $\mathbf{W}(i,j)$ – “distance measure” for nodes i and j
- Graph Partitioning:
 - Precise criterion
 - Efficient partition computation



Graph Partitioning

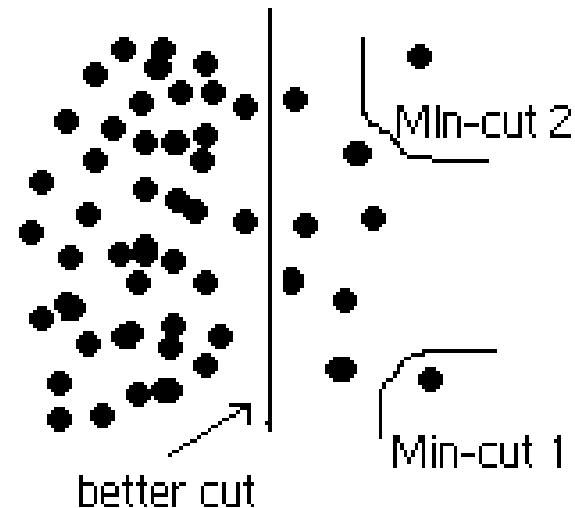
- Dissimilarity measure between two sets of graph $G=(V, E)$, $A \cup B = V, A \cap B = \emptyset$

$$cut(A, B) = \sum_{u \in A, v \in B} w(u, v)$$

- Minimum cut \implies Optimal bi-partitioning
- Clustering method (Wu, Leathy, PAMI 1993) that favors outliers
- Different cost function proposed:

$$Ncut(A, B) = \frac{cut(A, B)}{asso(A, V)} + \frac{cut(A, B)}{asso(B, V)}$$

$$asso(A, V) = \sum_{u \in A, t \in V} w(u, t)$$



Optimal Partitioning

- N – number of nodes in the graph V
- W – $N \times N$ symmetrical matrix with elements $W(i,j)$
- D : $d_i = \sum_j W(i,j)$ $D = \text{diag}(d_1, d_2, \dots, d_N)$
- x – indication vector: $x_i = \begin{cases} +1, & V(i) \in A \\ -1, & V(i) \notin A \end{cases}$
- Final result:
$$\min_x Ncut(x) = \min_y \frac{y^T (D - W)y}{y^T Dy}$$

with the condition:

$$y_i \in \left\{ 1 \frac{-\sum_{x_i > 0} d_i}{\sum_{x_i < 0} d_i} \right\}, \quad y^T \begin{bmatrix} d_1 \\ \vdots \\ d_N \end{bmatrix} = 0$$

Optimal Partitioning- con't

- Solution comes from eigenvalue system: $(D-W)y = \lambda Dy$
- Second constraint is satisfied for any eigenvector.

$$\curvearrowright D^{-1/2}(D-W)D^{-1/2}z = \lambda z \quad z = D^{1/2}y$$

- Symmetric, semi-positive definite – Laplacian matrix
- Using Rayleigh quotient and orthonormality of eigenvectors:
Real valued solution to the Normalized Cut problem is the second smallest eigenvector of the generalized eigensystem
- Graph is partitioned in two pieces using the second smallest eigenvalue
- Ideal case: the signs of vector elements tells us how to split



The Grouping Algorithm

- Use spatial proximity term and feature similarity terms to calculate weighted coefficients $W(i,j)$
- Summarize information in W and D
- Find an approximate solution for the second smallest eigenvalue of the system $(D-W)y = \lambda Dy$
- Bipartition the graph by finding the best splitting point
- Check the stability of the cut and decide on the current partition status
- Stop the recursion if Ncut exceeds certain limit

Experiments

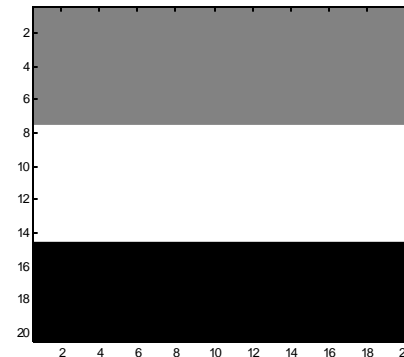
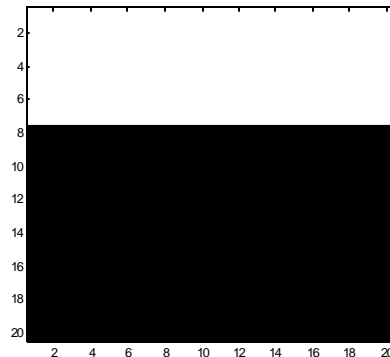
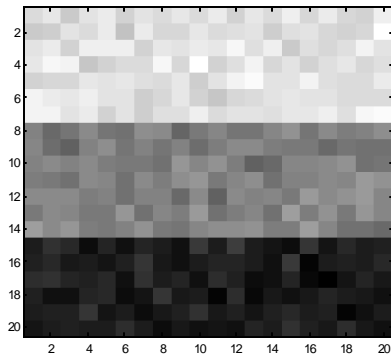
- Different parameter values and feature descriptors

$$W(i, j) = e^{-\frac{\|F_i - F_j\|_2}{s_I}} * e^{-\frac{\|X_i - X_j\|_2}{s_X}}, \quad \|X_i - X_j\|_2 < r$$

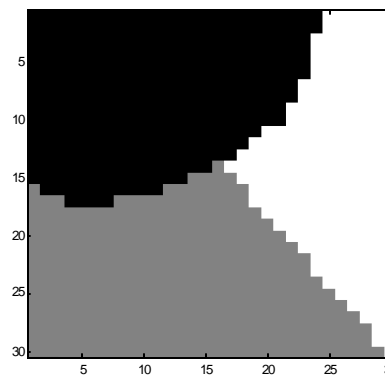
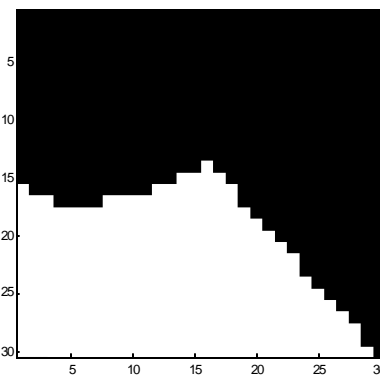
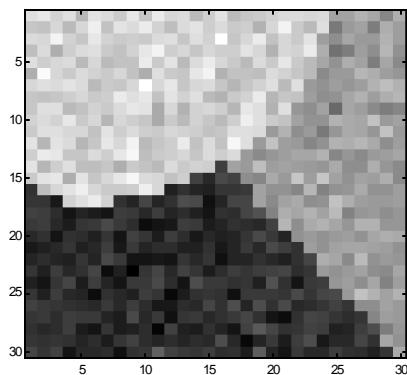
$$F(i) = \begin{cases} I(i), & \text{intensity} \\ [v, v \square s \square \sin(h), v \square s \square \cos(h)](i), & \text{color} \\ [|I * f_1|, \dots, |I * f_n|](i), & \text{texture} \end{cases}$$

Results

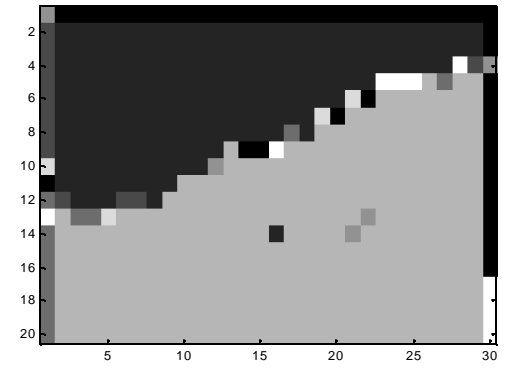
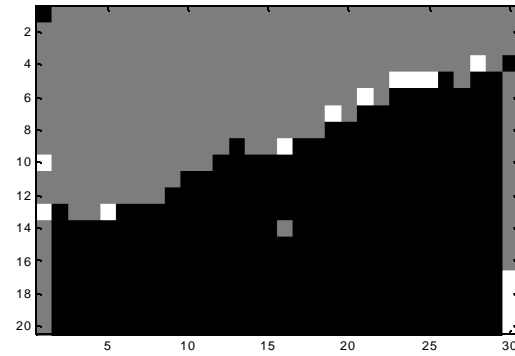
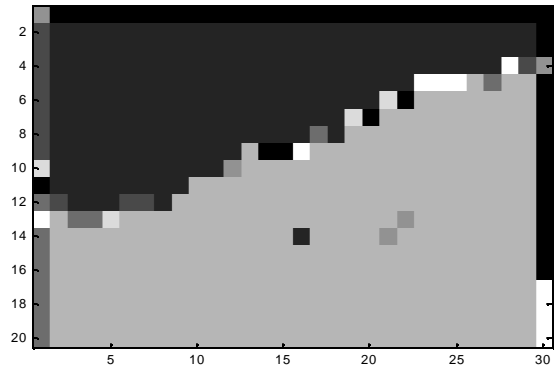
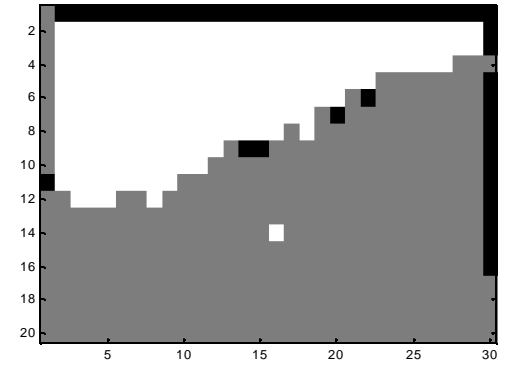
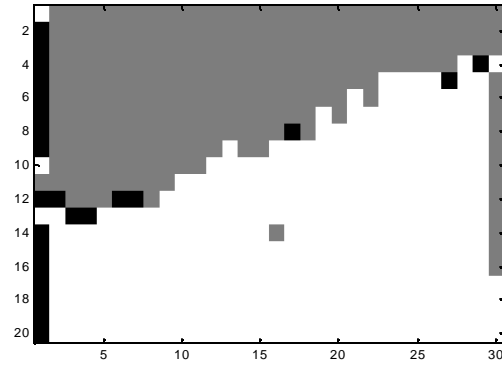
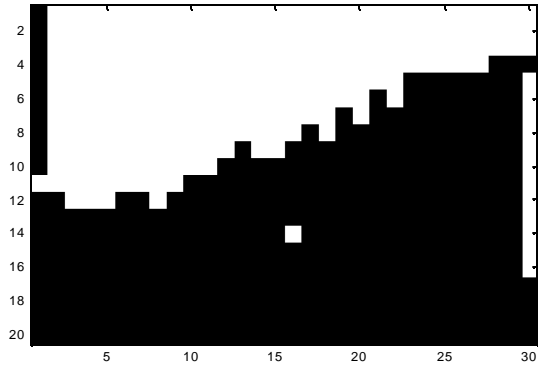
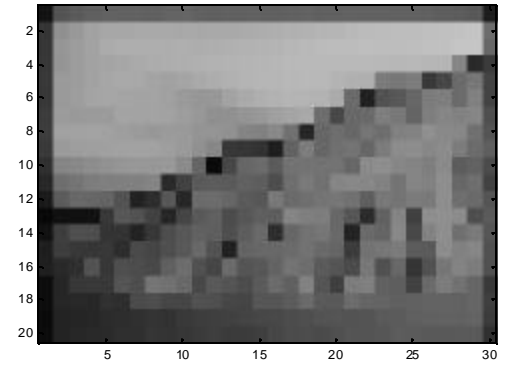
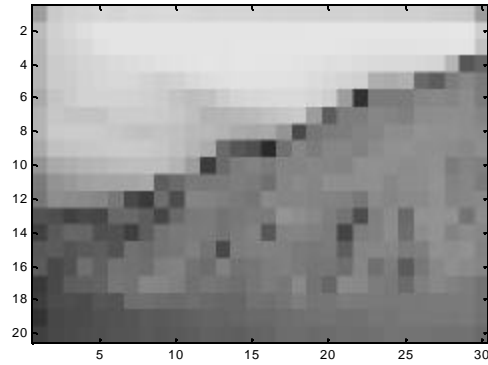
$$s = 0.1, r = 3.0, s_I = 0.02, s_X = 3.0$$



$$s = 0.1, r = 5.0, s_I = 0.01, s_V = 4.0$$



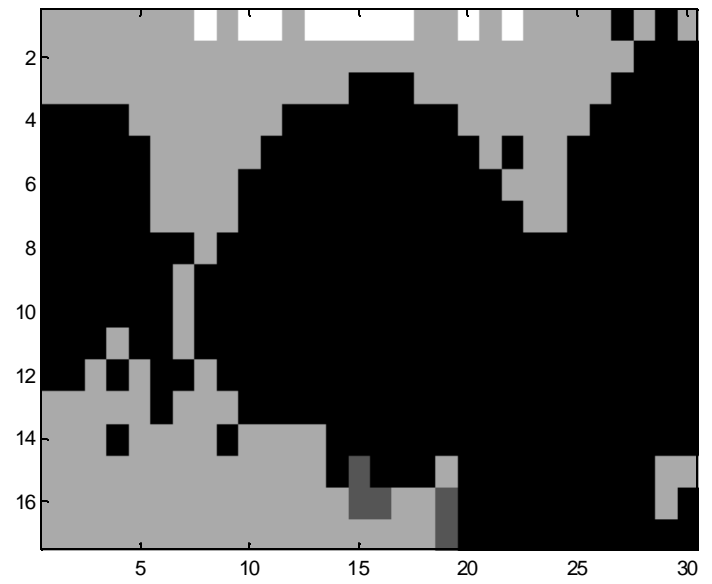
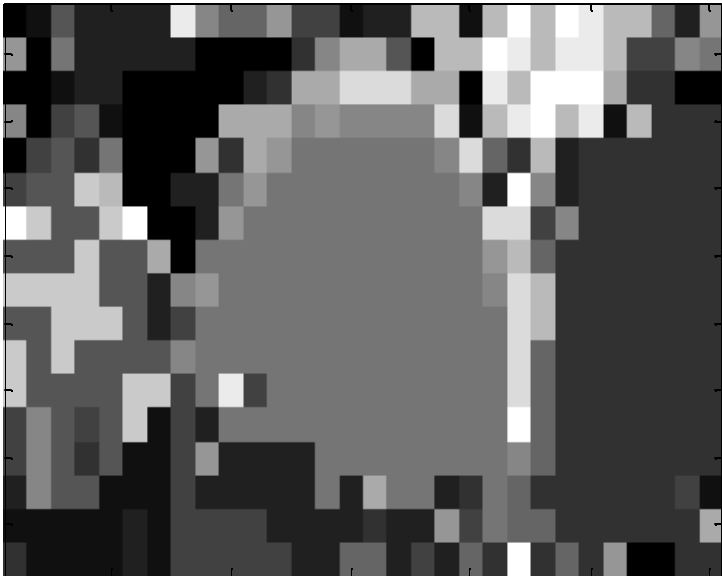
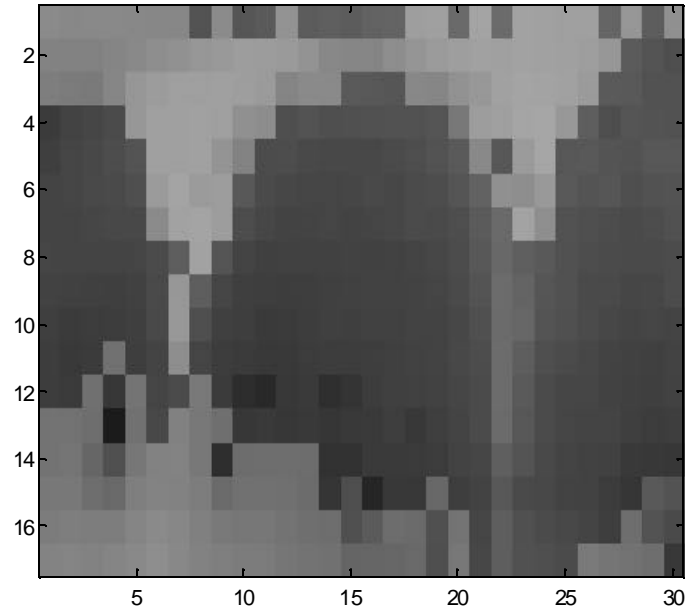
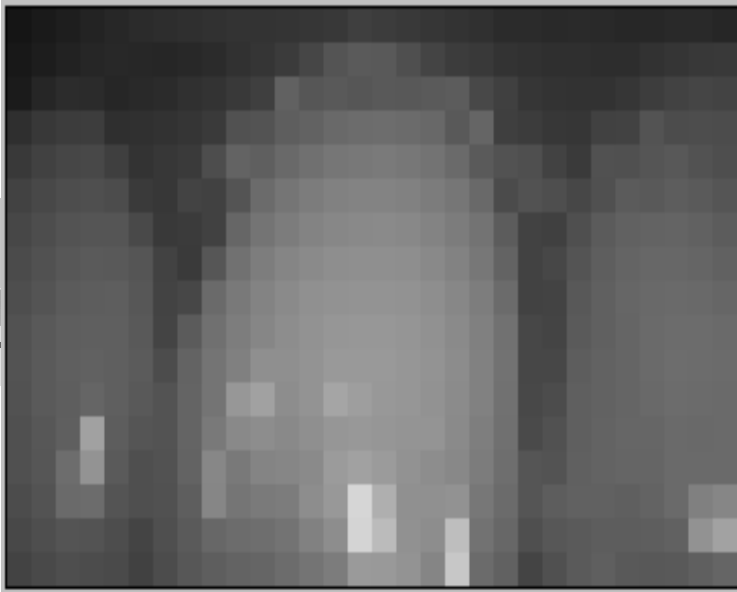
Normalized Cuts



June 8, 2000

Normalized Cuts

10



June 8, 2000

Normalized Cuts



Conclusion

- Computational Complexity
- Choice of Parameters
- Stability
- Heuristic methods
- Application